



**City of Coral Gables
CITY COMMISSION MEETING
September 11, 2018**

ITEM TITLE:

A Resolution accepting Miami-Dade County Transportation Planning Organization (TPO) Smart grant funds for the pedestrian and bike network level of stress assessment study.

DEPARTMENT HEAD RECOMMENDATION:

Approval.

BRIEF HISTORY:

The Department of Public Works was awarded an eighty thousand dollar (\$80,000) planning grant by the Transportation Planning Organization to complete a Pedestrian & Bike Network Level of Stress Assessment Study. The grant requires a local match of twenty thousand dollars (\$20,000).

The proposed stress assessment study will support the 2014 Commission adopted Bicycle and Pedestrian Master Plan by assessing qualitative aspects of the City’s existing and future bike network while also providing valuable pedestrian safety assessments. Measuring the comfort and experience of cycling and walking will help create a safer, low-stress network which attracts users of all ages and abilities. The study will analyze Coral Gables’ entire active mobility network and reference the Highway Capacity Manual’s assessment guidelines, as well as similar stress-level studies completed in other cities, to determine the quality, level of service, and stress level of the pedestrian and bicycle network. The study will also reference the National Association of City Transportation Officials (NACTO) latest design standards to serve as a benchmark in determining possible improvements which could be incorporated into Coral Gables’ active mobility network.

Project Schedule – 6 months total

Task	Length
Data Collection	2 months
Analysis	1 month
Draft of recommendations/findings	1 month
Multi-agency review and comments	1 month
Public comment period/Final draft	1 month

FINANCIAL INFORMATION:

No.	Amount	Account No.	Source of Funds
1.	\$20,000 (local match)	350-1553-541-63-00	Roadway Funds
2.	\$80,000		TPO Grant
Total:	\$100,000	APPROVED BY:	

Attachments:

1. Proposed Resolution
2. Grant Application
3. Consultant Proposal